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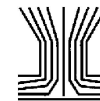
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Skylight Color Shifts due to Variations of Urban-Industrial Aerosol Properties: Observer Color Difference Sensitivity Compared to a Digital Camera

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Simulations of the sky dome color shifts of a cloudless sky have been performed, assuming three urban-industrial tropospheric aerosol cases. Each of these aerosols is represented by the bimodal lognormal volume distribution (Dubovik et al. 2002). A total of ten parameters are used to control the aerosol characteristics. These ten parameters are perturbed and the resulting sky color shifts are estimated. All simulations have been performed relative to the reference cases that represent the time-averaged state of each aerosol case. We have simulated the sensitivity of the theoretical CIE (Commission Internationale de l'Éclairage) standard human observer to discriminate sky color changes, due to changes of the aerosol control parameters. A Digital color Camera Model (DCM) has also been incorporated in the simulation scheme. The DCM simulates the performance of a camera-colorimeter created specifically to measure sky color. The DCM has been used to investigate whether a color digital camera can replicate the behavior of the CIE standard observer, with respect to sky color shifts. The standard observer is most sensitive to perturbations of the parameters of the aerosol fine mode, which are particles with diameters less than $0.6 \mu\text{m}$. However his sensitivity is highly variable, depending on the parameter varied, on the aerosol case and on the direction of the observation. The DCM was in excellent agreement with the behavior of the CIE standard observer. The camera simulated sky color measurement accuracy was high. The results show that the camera sensitivity in discriminating color differences is much better than that of the observer.

1. INTRODUCTION

Atmospheric aerosols affect visibility (Seinfeld and Pandis 1998) by scattering and absorbing radiation within the atmosphere. The net result of these processes can be to degrade visibility—the impairment of atmospheric clarity or the ability to perceive form, texture, and color (Trijonis et al. 1990). The

radiance of the sun-illuminated atmosphere, traversing through layers of air, forms the stimulus responsible for the sensation of the observed color. The interaction of radiation with aerosol particles alters the observed color of the sky dome (Adams et al. 1974; Dave 1980; Dave 1981; Tsay et al. 1991; Dogras et al. 2004). The concept of visibility is mostly reflected by visual range (Trijonis et al. 1990). However, visual range represents the overall visual experience of an observer when viewing a scene. Scenic beauty and visual air quality, apart from being sensitive to visual range, are also dependent on sky color (Latimer et al. 1981; Watson 2002). Visibility when related to visual range is a well-studied subject (EPA 1979; Trijonis et al. 1990; Pitchford and Malm 1994; Henry 2002), while the effect of atmospheric pollution and specifically, that of tropospheric aerosols, on the sky or skylight color has not been fully addressed yet.

Dave, almost four decades ago, published a series of articles that are considered fundamental to the transfer of visible radiation in the atmosphere, in which he describes how he simulated the chromaticities of the clear skies (Dave and Mateer 1968; Dave 1978, 1980, 1981). In his papers, Dave stresses the importance of atmospheric aerosols in determining sky color and the variability of that color for various viewing directions relative to the sun.

The importance of stratospheric ozone, especially on the color of twilight, was also reported by early studies (Dave and Mateer 1968; Adams et al. 1974). Realistic rendering of the earth's atmosphere and the colors of the sky dome requires the inclusion of ozone and aerosols in the simulations (Jackel and Walter 1997; Sloup 2002; Haber et al. 2005). The aerosol models used in the above articles are too simplified to meet the needs of current environmental research. Dogras et al. (2004) have recently presented a study on the discoloration of the sky over cities that emphasize the role of urban aerosols. Because they have investigated the problem of daylight radiation that passes through a haze layer and not that of skylight, the geometry of the problem is greatly simplified and their method is unsuitable for specifically simulating skylight color.

In 1980, MacAdam published an article that introduced colorimetric theories in relation to visual air quality studies (MacAdam 1980). Although characterization of visibility of

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landscapes has progressed since then, and newer concepts like the deciview unit (Pitchford and Malm 1994; Watson 2002; Henry 2002) are now available, many of his suggestions are valuable when applied to sky color. Since we want to investigate the sensitivity of the human perception to sky color changes, due to variations of the aerosol properties, the concept of colorimetrically defined Just Noticeable Differences (JNDs) is very useful.

Color is the human sensation stimulated by the visual electromagnetic radiation. Therefore there is no color without an observer (Sharma 2003). Since it is important only for human vision it can only be defined by reference to visual functions (MacAdam 1980). Unfortunately perception of color is variable and subjective (Wyszecki and Stiles 1971; Pratt 1978) and only rough unreliable descriptions of color memories can be obtained by observers a short time after observing a particular color (Bodrogi and Tarczali 2001). Alteration of the characteristics of the scattering and absorbing atmospheric particulate matter is perceived by humans as shifts of sky color, relative to their memory of the previously observed atmospheric state. A system that consistently over time records and measures sky color is valuable and can overcome the human observer uncertainty.

In this study, we present a method for evaluating the effects of aerosols on the color of the sky and, at the same time, the sensitivity of the observer to these changes. Instead of simulating various radiation fields of the sky dome, followed by application of colorimetric formulas to estimate color coordinates, we take the novice approach to include the measuring procedure in our simulation. This is accomplished by incorporating a camera model in our simulation schematic. We believe that it is important to know not only the sensitivity of sky color to aerosol loading but also the limitations of the instrumentation used to record color, as well. This approach allows us to study the reaction of the theoretical “standard human observer”¹ (Broadbent 2008; Pratt 1978) to the skylight stimulus and at the same time the response of the camera device to that same stimulus. This is of particular interest, since the camera is a much more feasible and realistic approach than the theoretical observer in quantifying sky color shifts.

The presented method and the results focus on the effect of urban-industrial aerosols on the color of the sky. These aerosols have an impact on the large populations living in cities all around the world. We are interested in the sky color shifts imposed by variations of the size distributions and optical properties of urban-industrial aerosols. However, other types of aerosols (e.g., continental or oceanic) are the subject of on going research as the method we use can easily utilize other types of aerosols. Humans living in the cities comprehend visual air quality deterioration

due to atmospheric pollution, from the color of the sky and less through visibility deterioration, as most of the times nearby buildings put out of sight distant objects. Since different urban environments result in different aerosol characteristics, we have used three aerosol cases to describe particulate matter in the atmosphere. These are extracted from real case studies at various regions of the world (Dubovik et al. 2002). A detailed description is given in Section 2.1.

When rendering the sky color relative to atmospheric aerosols, various approaches are available. In computer graphics, color images of rendered outdoor scenes at a variety of aerosol types were presented (Jackèl and Walter 1997; Haber et al. 2005). In some cases color characteristics of the sky are calculated for various mixtures of pure and composite particles (Tsay et al. 1991; Dogras et al. 2004). It is also common to simulate sky color for a pure Rayleigh scattering atmosphere, relative to various aerosol containing atmospheres (Adams et al. 1974; Dave 1980, 1981). Our method is different. We use the concept of the “reference case” to describe the time averaged or common characteristics of the aerosol for the particular aerosol case. We then perturb each of the aerosol control parameters relative to the reference case and estimate the shift of the sky color. This is a much more realistic approach since cities are constant sources of particulate matter and pristine visual quality conditions are not representative of the actual conditions.

The use of camera systems in environmental research is common. Cameras have been used in the past in experimental studies on scenic beauty appreciation, when related to visual air quality (Latimer et al. 1981). A very common application is the monitoring and simulation of visibility reduction (Malm et al. 1983; Larson et al. 1988; Trijonis et al. 1990; Molenar et al. 1994; Eldering et al. 1993, 1996). Recorded color photographs of outdoor scenes, form the basis for producing synthetic ones that simulate the effects of atmospheric haze. In all cases, portions of the sky are included in both the real and the simulated images. However these studies focus on the reduction of visibility of distant objects as seen through atmospheric haze and not on the faithful reproduction or estimation of the color of the sky. Photographic methods are also used for estimating the transmittance of the atmosphere (Richards et al. 1989). Digital cameras combined with the appropriate image processing algorithms have been utilized as instruments for measuring visual range (Luo 2005; Bäumer et al. 2007). A photographic technique has also been used for plume detection against the sky background (Du et al. 2007).

When an accurate color measurement of the sky is sought, spectroradiometers (Hernández-Andrès et al. 1999; Hernández-Andrès and Romero 2001) are used. On the other hand cameras can be used to systematically record visual pollution incidents for qualitative assessments. Another highly desirable feature of any camera is the high angular and temporal resolution (Hernández-Andrès et al. 2003), which results in a vast number of sky color measurements delivered at a fraction of time and cost, when compared against spectroradiometers. The photographs of the sky dome recorded by a camera are of great

¹In this article the “standard human observer” is an observer with normal color vision that is compatible with the CIE (Commission Internationale de l’Eclairage) standards of color especially when referring to the Just Noticeable Difference Concept (JND). CIE is the primary organization responsible for standardization of color metrics and terminology (Sharma 2003).

archival value. However, in order for a camera to accurately measure sky color, it has to be calibrated specifically for the sky targets. The accuracy of its measurements has to be known beforehand as well. This type of camera is more a scientific instrument and less a photographic equipment. In the film era the construction of such a system was too complicated and the measurements were time consuming. Nowadays, digital cameras simplify such a task. Combinations of camera and spectroradiometers are used to record sky color (Lee 1994; Lee and Hernández-Andrès 2003) and to investigate color and luminance asymmetries of the sky dome (Hernández-Andrès et al. 2003). A study for designing a camera system for spectral imaging of the skylight has been presented recently (López-Álvarez et al. 2005).

In our previous work (Haralabidis and Pilinis 2005) we have studied the desired features of a camera specifically designed to accurately record the color of the sky dome. We have shown that a color camera, equipped with a consumer digital image sensor, and combined with the appropriate imaging pipeline, can be used as a tristimulus colorimeter that is specifically intended to measure sky color. Part of our study was to build a Digital Camera Model (DCM) to simulate the performance of the real camera-colorimeter, by including color retrieval accuracy and measuring limitations. The camera output is the color coordinates of skylight from a specific point of the sky dome and the accuracy of that measurement. The DCM was included in our model to simulate the measuring procedure.

It is evident that a flexible model which simulates the sky color for a variety of aerosols, atmospheric profiles and sun observation path geometries is a multivariable problem. When combined with instrumentation modeling and investigation of the reaction of human sensation to perceived color changes, it becomes a fundamentally challenging task. In the following sections we give a detailed description of the simulation scheme and present the results from the application of the model.

2. THE SIMULATION PROCEDURE

The flow diagram of the system we have created in order to simulate sky colors and the measuring procedure is depicted in Figure 1. A feature of our simulation scheme is the modular architecture. The main components are the Aerosol Optical Properties Module (AOPM), the Radiative Transfer Module (RTM) and the DCM (Adams et al. 1974; Dave 1980; 1981; Tsay et al. 1991; Sloup 2002; Lee and Hernández-Andrès 2003; Haber et al. 2005).

In order to simulate sky color it is necessary to simulate the radiation field of the sky. To do so we first have to estimate the optical properties of the aerosol populations. The module that calculates the optical properties of the aerosols is AOPM and includes a Mie scattering code. Results from AOPM are forwarded to the RTM module (Figure 1) in order to parameterize the atmosphere through which radiation traverses. RTM consists of two parts. The radiative transfer code itself and an interface for the code. All radiative transfer calculations were performed

using the MODTRAN code (Berk et al. 2003), combined with an appropriate control interface engineered using the Mathematica software. RTM output are the sky spectral radiances. Calculated radiances are redirected to the DCM module in order to simulate color recording by the camera. The DCM also estimates the theoretical values of that color, as well as the color recording accuracy of the camera, for each measurement. Apart from the MODTRAN code all modules were created using the Mathematica software.

2.1. The Aerosol Cases

In our simulations, we have included three urban-industrial aerosols, Mexico City, Creteil, Paris, and Maldives. The aerosol properties are derived from ground based indirect remote sensing measurements of the Aerosol Robotic Network (AERONET) (Holben et al. 1998). These three urban aerosols correspond to three completely different areas of the world and they are the result of different emissions, chemical reactions, and geophysical-meteorological characteristics (Dubovik et al. 2002). A detail description of these aerosol cases is given by Dubovik et al. (2002). Mexico City exhibits the higher pollution levels among the three reference cases. Creteil, Paris aerosol exhibits the lowest real part of the refractive index (Table 1), usually associated with higher relative humidity and resultant hygroscopic growth. The pollution of Creteil, Paris is closer to water-soluble aerosols than the Maldives and Mexico City aerosol cases. Emission controls of car and industrial pollution is more advanced in France than in Mexico and India (Dubovik et al. 2002). Aerosol from Maldives has contributions from sea salt and from long-distance transport of airborne soil dust (Eck et al. 2001). We want to investigate how an observer will respond to sky color shifts resulting from variations of the aerosol characteristics in these different locations. We utilized aerosol characteristics created from the AERONET data, since their measuring procedure is similar to the simulated sun-observer path geometry of our study (Figure 2). Aerosol size distributions derived by AERONET are well suited to our simulation scheme. The inversion procedure of Dubovik and King (2000) retrieves the “optical” size distribution from the light scattered and absorbed by particles. In this study we use these “optical” sizes to calculate the scattering and absorption of light by particles.

The effect of aerosol particles on radiative transfer depends on their size distribution and chemical composition (Pilinis and Li 1998; Molnár and Mészáros 2001). In practice, aerosols are a collection of discrete sized particles with a number concentration that depends on the aerosol size. Such a polydispersion can be described as the sum of log-normal distributions (Seinfeld and Pandis 1998). We have used the bimodal lognormal function of the volume distribution (Dubovik et al. 2002):

$$\frac{dV(r)}{d \ln r} = \sum_{i=1}^2 \frac{C_{v,i}}{\sigma_i \sqrt{2\pi}} \exp \left[-\frac{(\ln r - \ln r_{v,i})^2}{2\sigma_i^2} \right] \quad [1]$$

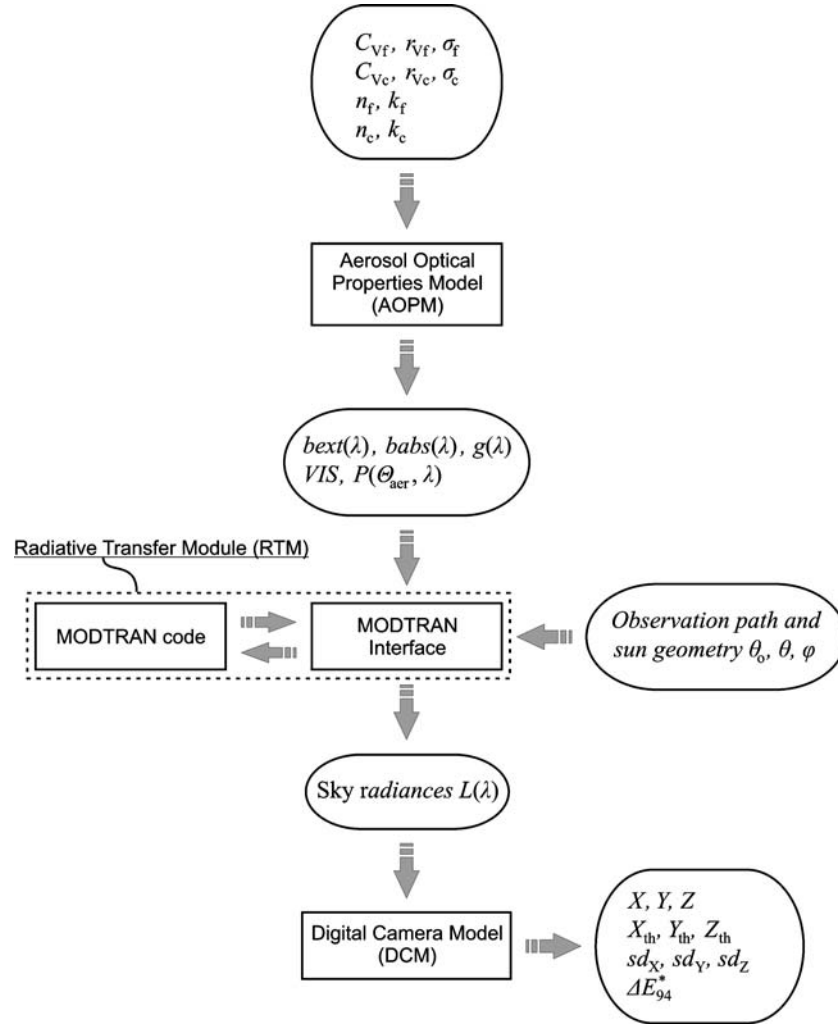


FIG. 1. Flow diagram of the sky color simulation system.

where $dV(r)/d \ln r$ ($\mu\text{m}^3 \text{m}^{-3}$) is the aerosol volume distribution, r (μm) denotes the particle radius, $C_{V,i}$ ($\mu\text{m}^3\text{m}^{-3}$) the particle total volume concentration, $r_{V,i}$ (μm) is the median radius, and σ_i is the geometric standard deviation. In the above equation index i represents the two aerosol modes, termed as fine “f” ($0.05 \leq r \leq 0.6 \mu\text{m}$), and coarse “c” ($0.6 \leq r \leq 15 \mu\text{m}$). The size range is considered between 0.05 and 15 μm ($0.05 \leq r \leq 15 \mu\text{m}$). We assume that beyond those limits the aerosol concentration drops to zero. For radiative transfer calculations aerosol chemical composition is characterized by a complex refractive index, m (Piliinis and Pandis 1995):

$$m = n + Ik \quad [2]$$

n, k being the real and the imaginary part of m . Six parameters are used to control the two modes of the aerosol distribution, C_{Vf}, r_{Vf}, σ_f for fine and C_{Vc}, r_{Vc}, σ_c for coarse. If we include n and k for the fine (n_f, k_f) and coarse (n_c, k_c) modes, a total of

ten control parameters are used to completely characterize the aerosol model. Details of the numerical values of the aerosol models used in this study are listed in Table 1. According to the description of the three aerosol cases, m is considered independent of light wavelength λ . The original model is dynamic and most of the parameters are functions of the aerosol optical thickness, $\tau(\lambda)$. All reference cases were estimated from the mean optical thicknesses at 440 nm, $\langle \tau(440 \text{ nm}) \rangle$ (Figure 3). We have decided to test all possible aerosol volume distribution parameters that are likely to affect the observer sensitivity to sky color shifts. Each control parameter is varied, relative to the reference case, while keeping the values of the rest of the parameters fixed (Table 1). We have used the described ranges of the aerosol parameters in order to clarify the issue of whether the observer can comprehend a color shift due to a change of an aerosol parameter or not. A detailed description of the relation of the observer sensitivity to color differences and b_{ext} is presented in Section 3.

TABLE 1
Summary of the three urban–industrial aerosol models used in this study

Parameters	Creteil, Paris, France $\langle\tau(440)\rangle^a = 0.26$		Mexico City $\langle\tau(440)\rangle^a = 0.43$		Maldives (INDOEX) $\langle\tau(440)\rangle^a = 0.27$	
	Base case	Range of variation (%)	Base case	Range of variation (%)	Base case	Range of variation (%)
Median radius r_{vf} (μm)	0.144	–90%–200%	0.137	–90%–200%	0.180	–90%–200%
Volume concentration C_{Vf} ($\mu\text{m}^3\text{m}^{-3}$)	2.379×10^7	–90%–200%	3.074×10^7	–90%–200%	1.754×10^7	–90%–200%
Standard deviation σ_f	0.430	–30%–200%	0.430	–30%–200%	0.460	–30%–200%
Median radius r_{vc} (μm)	2.885	–90%–200%	2.978	–90%–200%	2.785	–90%–200%
Volume concentration C_{Vc} ($\mu\text{m}^3\text{m}^{-3}$)	1.328×10^7	–90%–200%	2.818×10^7	–90%–200%	2.192×10^7	–90%–200%
Standard deviation σ_c	0.790	–30%–200%	0.630	–30%–200%	0.760	–30%–200%
Real refractive index ^b	1.400	–5%–13%	1.470	–9%–9%	1.440	–8%–12%
n_f, n_c						
Imaginary refractive index ^b k_f, k_c	0.009	–100%–60%	0.014	–100%–50%	0.011	–100%–90%

^aAerosol average optical thickness values at 440 nm used to estimate base cases (Dubovik et al. 2002).

^bBoth fine and coarse modes of the base cases are considered to have the same n and k .

This study focuses on the volume concentration of the aerosol and as a result the performed perturbation of some of the parameters affects the total number and the number distribution of either the fine or the coarse mode of the aerosol. The effect of the above is analytically discussed in Section 3.

Since aerosol volume distributions $dV(r)/d \ln r$ are reported (Dubovik et al. 2002) as the total column aerosol content ($\mu\text{m}^3 \mu\text{m}^{-2}$), we have to use optical thickness scaling factors to convert them into ($\mu\text{m}^3 \text{m}^{-3}$). In our case the scaling factors were calculated by iterating MODTRAN with the reference case

aerosol distribution shape, in order to converge to the observed aerosol optical thickness of Dubovik et al. (2002). A similar approach has been followed by Remer et al. (1997). Figure 3 presents the volume size distribution for each of the reference cases after scaling.

2.2. Absorption and Scattering of Light by Atmospheric Aerosols

We have developed our own Mie scattering code using the Mathematica package (Figure 1). We assumed spherical homogeneous particles characterized by a complex refractive index (Dubovik et al. 2002). The assumption of sphericity is consistent with the previously described aerosol cases (Dubovik and King 2000; Dubovik et al. 2002). Module inputs are the ten aerosol control parameters described in Section 2.1. Module outputs are the wavelength dependent aerosol extinction coefficients $b_{ext}(\lambda)$ (km^{-1}), absorption coefficient $b_{abs}(\lambda)$ (km^{-1}), aerosol asymmetry parameters $g(\lambda)$, surface meteorological visibility range VIS (km), and the aerosol phase functions $P(\theta_{aer}, \lambda)$. Since we are interested in the visible portion of radiation, light wavelengths λ , are considered between $\lambda_{min} = 360$ nm to $\lambda_{max} = 830$ nm. The above quantities are required by MODTRAN.

2.3. Radiative Transfer Calculations

For simulating atmospheric radiance fields we use MODTRAN, which offers extensive parameterization to allow custom user control. The outputs of the radiative transfer code are the sky spectral radiances $L(\lambda)$. These radiances are forwarded to the DCM module in order to estimate the skylight color.

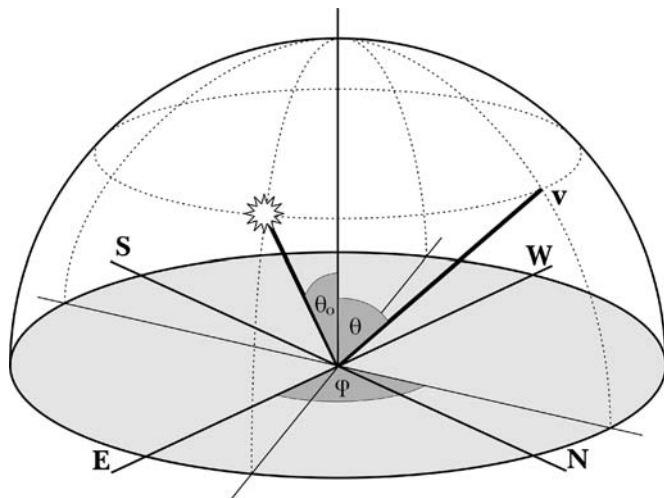


FIG. 2. Simulation geometry and the sky dome. The star shape marks the position of the sun and v marks the observer or camera viewing path.

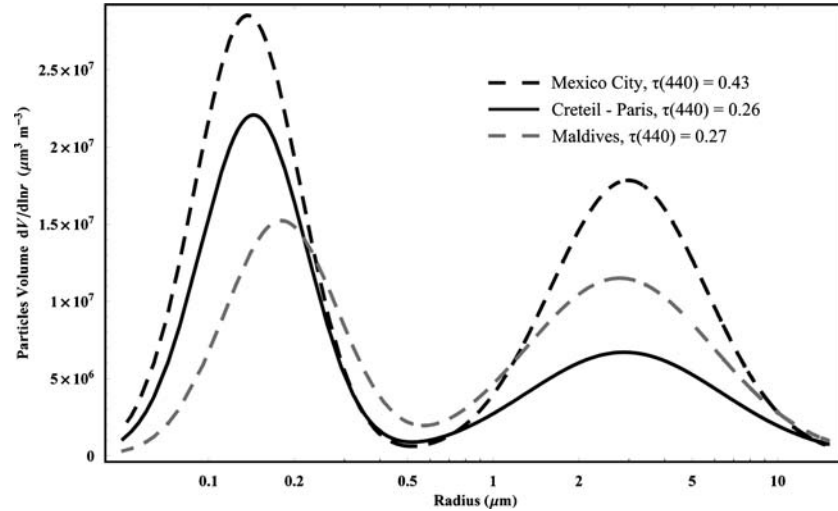


FIG. 3. Aerosol volume distributions for the three reference cases.

Figure 2 presents the geometry of the simulation. Let θ_0 being the sun zenith angle, θ being the observation line of sight and ϕ being the azimuth angle between the sun to observer path and the line of sight. To minimize possible uncertainties due to aerosol vertical variations (Dubovik and King 2000), we focus our analysis on simulating sky radiances at the solar almucantar (zenith angle of observations is equal to the solar zenith angle). All simulated measurements are performed for sun zenith angle of 72.5° , corresponding to morning and late afternoon hours.

Multiple scattering and refraction of light rays through the atmosphere are considered in our calculations. The effects of scattering by air molecules and by a reflecting surface are also included in the software parameterization. We used the mid-latitude standard atmosphere, a cloudless sky and surface albedo termed “urban” as defined in MODTRAN.

2.4. The Digital Camera Model

We have developed a DCM with the purpose of simulating the performance of a sky radiance colorimeter, based on a single-sensor camera. A detailed description of the DCM, as well as a presentation of its colorimetric performance is presented elsewhere (Haralabidis and Pilinis 2005). The DCM simulates the performance of the Kodak KAF-5101CE CCD sensor (Eastman Kodak 2003), equipped with a three color filter mosaic (Red, Green, and Blue, RGB). Analog to digital conversion is performed at 12-bit of accuracy. To achieve accurate color recording, we utilized a least squares color characterization method, using sky specific radiance training sets. The method we developed especially for this purpose is termed as Sky Radiance Sky Point Preserving Least Squares (SkyRadSPPLS) and it is a variation of the constrained least square methods (Finlayson and Drew 1997). The accuracy of the SkyRadSPPLS method was tested using 912 sky spectral radiance samples generated

by MODTRAN. These samples represented a variety of atmospheric conditions and viewing directions. The SkyRadSPPLS method had an excellent performance with 73.5% of the samples recorded at an accuracy of less than 1/10 of the CIE-94 unit, while all of the samples were less than 1/2 of the CIE-94 unit (details of the CIE-94 unit are given in the next section). The DCM also simulates the uncertainties introduced during the measuring procedure due to various sources of noise. DCM input is radiance. The outputs of the DCM are the tristimulus XYZ color values based on the 2° 1931 CIE standard observer, coupled with the uncertainty of these measurements. A short description of the colorimetric terms and terminology used in this study is given in the next section.

2.5. Colorimetry

In this study we calculate the sky spectral radiances $L(\lambda)$ in order to simulate sky color. In the trichromatic color system, color is described in terms of tristimulus values. Let \bar{x}_λ , \bar{y}_λ , and \bar{z}_λ be the 2° 1931 CIE Standard Observer color matching functions. The tabular form of these functions is provided by many authors at 5 nm intervals (e.g., Sharma 2003). Straightforward estimation of the CIE 1931 tristimulus values X , Y , Z is given by:

$$X = \int_{\lambda_{\min}}^{\lambda_{\max}} L(\lambda) \bar{x}_\lambda d\lambda \quad [3a]$$

$$Y = \int_{\lambda_{\min}}^{\lambda_{\max}} L(\lambda) \bar{y}_\lambda d\lambda \quad [3b]$$

$$Z = \int_{\lambda_{\min}}^{\lambda_{\max}} L(\lambda) \bar{z}_\lambda d\lambda \quad [3c]$$

From the above equations we can estimate the theoretical values X_{th} , Y_{th} , and Z_{th} of color from a particular point of the sky dome.

A desirable characteristic of any color coordinate system is its perceptual uniformity. That means that equal changes of colors of that system should be perceived as equivalently noticeable color shifts to an observer. Although the CIE XYZ color system is used to unambiguously represent color, it is perceptually nonuniform (Pratt 1978). Uniform color spaces are a field of active research. CIE has recommended a uniform color space called the CIE 1976 $L^*a^*b^*$ system, which is widely used in color imaging and easily derived from the CIE XYZ system (Sharma 2003). In the $L^*a^*b^*$ coordinates, L^* is the lightness component of the color. The Euclidean distance between two color stimuli of coordinates L_1^*, a_1^*, b_1^* and L_2^*, a_2^*, b_2^* , respectively, represents the color difference and is given by:

$$\Delta E_{Eu}^* = \sqrt{(L_2^* - L_1^*)^2 + (a_2^* - a_1^*)^2 + (b_2^* - b_1^*)^2} \quad [4]$$

It is reported that a ΔE_{Eu}^* value of around 2.3 corresponds to a JND (Mahy et al. 1994). Unfortunately uniformity of the $L^*a^*b^*$ color system has been proven to be limited (Sharma 2003). Alternative color difference formulae have therefore been proposed. In 1994 CIE proposed a formula, termed as CIE-94 color difference formula, based on the $L^*a^*b^*$ color system. A detailed description of this formula can be found elsewhere (e.g., Sharma 2003).

Color difference ΔE_{94}^* has units smaller than ΔE_{Eu}^* . Although in many practical cases a ΔE_{94}^* unit value is assumed to correspond to a JND, there is no definite statement in the scientific literature that this is the case. Therefore it is preferable to use the term one ΔE_{94}^* unit instead of a JND. CIE has defined the reference conditions under which the CIE-94 metric performs well (CIE 1995). One of the conditions states that color specimens whose perceptual color difference is evaluated must be viewed by the assessor when placed side by side. Since in our case sky color shifts due to variation of atmospheric optics occur at different times of the day and they are as a result cannot be observed simultaneously, it is reasonable to expect that the color difference of one ΔE_{94}^* unit is much lower than the actual color difference perception of the observer (Bodrogi and Tarczali 2001). In our study we used the one ΔE_{94}^* unit threshold as a worst case scenario. In actual situations this limit is expected to be much higher.

3. RESULTS AND DISCUSSION

3.1. Model Operation

The simulations were performed according to Section 2. All three aerosols of the simulations are controlled by 10 different parameters and each one is independently varied relative to the reference case. The sky color also changes relative to the sun-observer and observation path geometry. Since obser-

vations are restricted to the solar almucadar, sky color geometry is controlled only by the azimuth angle φ . We have performed our simulations for three different φ values, 30° , 90° , and 120° . Consequently thirty sets of simulations were performed for each aerosol scenario. Each set consists of a variable number of synthetic photographs. Every photograph was produced from a unique combination of aerosol parameters, azimuth angles, and aerosol scenarios.

We have produced each set of synthetic photographs, related to variation of a single control parameter, while keeping camera exposure steady. Exposure was controlled by adjusting exposure time. We wanted to avoid saturating the sensor red, green, or blue color channels. Hence camera exposure was defined to raise a maximum of 87.5% of the saturation signal for any of the channels. In order to take advantage of the camera dynamic range, we attributed the above maximum to the radiance that raised the higher signal for the camera channels. All other photographs of the same set were produced under lower lighting conditions. As a result, the lightness parameter L^* of the recorded color, changes during the variation of an aerosol control parameter. Accordingly, observer color differences and camera performance results, which are presented in the following sections, also take into account changes of the lightness of the color. Because of these changes of lightness, the camera noise performance is not stable. Darker colors are related to lower signal levels at the sensor and therefore have poorer signal-to-noise ratios than lighter colors. Camera evaluation is performed for two different criteria. We investigate the ability of the camera to replicate the behavior of the standard observer, relevant to detection of sky color shifts (section 3.3) and we study camera sensitivity to positively detect sky color changes related to perturbation of the aerosol parameters (section 3.4).

3.2. Observer Sensitivity to Variations of the Aerosol Parameters

We have simulated the perception of the standard observer to sky color shifts due to changes of the aerosol control parameters. We have also evaluated the reliability of the camera to approach the behavior of the standard observer. Figures 4 and 5 illustrate the results from implementing the CIE-94 formula to the theoretically calculated X_{th} , Y_{th} , Z_{th} tristimulus values together with the simulated X_{rec} , Y_{rec} , Z_{rec} measurements of the camera for Mexico City and Creteil, Paris aerosol. The behavior of the Maldives (INDOEX) aerosol is similar and therefore not presented. It is shown that observer sensitivity on color shifts greatly depends on the varied aerosol parameter. A more detailed description is presented in Table 2. We estimated the minimum–maximum percentage range of aerosol control parameter variation, relative to sky color shifts, which remain unperceivable by the observer. Table 2 was calculated using the theoretical tristimulus values. All % changes of the aerosol control parameters presented result in color differences lower than the threshold of one ΔE_{94}^* unit. According to Figures 4 and 5 in all cases, the observer is more

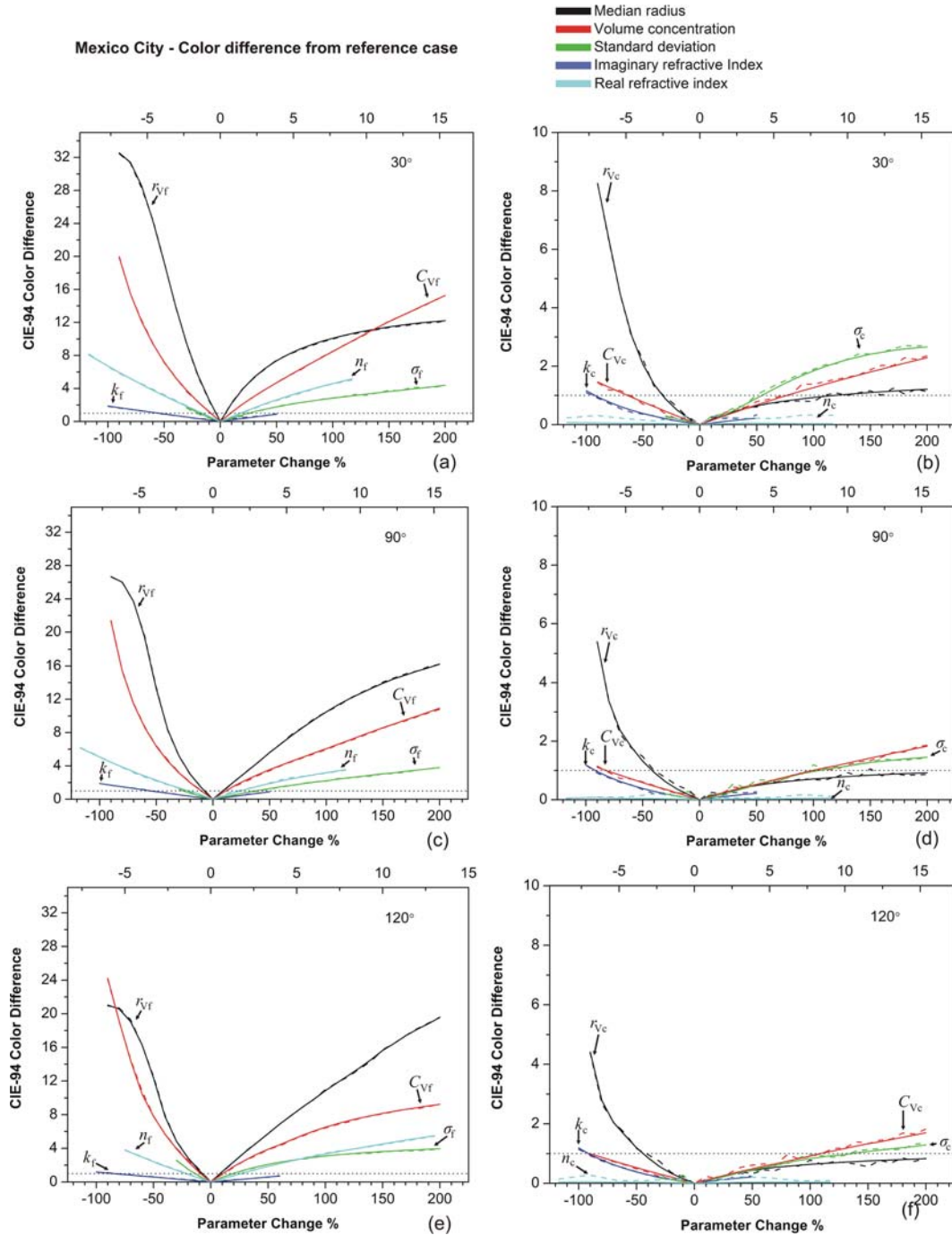


FIG. 4. CIE-94 color difference for the Mexico City aerosol case. Estimated theoretical values (solid lines) and camera measurements (dashed lines). Plates (a), (c), and (e) present the fine mode parameters. Plates (b), (d), and (f) show the coarse mode parameters. The dashed black line intercepts color difference lines at a value of $1 \Delta E_{94}^*$ unit. The n_f curve corresponds to the top x axis and all other curves to the bottom x axis.

sensitive to variations of the fine mode aerosol distribution control parameters than he is to the corresponding changes of the coarse mode. This is due to the fact that for the spectral range under consideration (360 nm–830 nm) light is scattered much more efficiently by fine mode ($<0.6 \mu\text{m}$) particles (Seinfeld and Pandis 1998; Dubovik et al. 2002).

3.2.1. Variation of the Median Radius r_{vf} and r_{vc}

From Figures 4 and 5 it is evident that both sky color and the observer perception of this color are very sensitive to changes of the median radius of the fine mode r_{vf} for all aerosols. When decreasing the value of r_{vf} from the reference case, color differences are more abrupt than when increasing the value (Figures 4

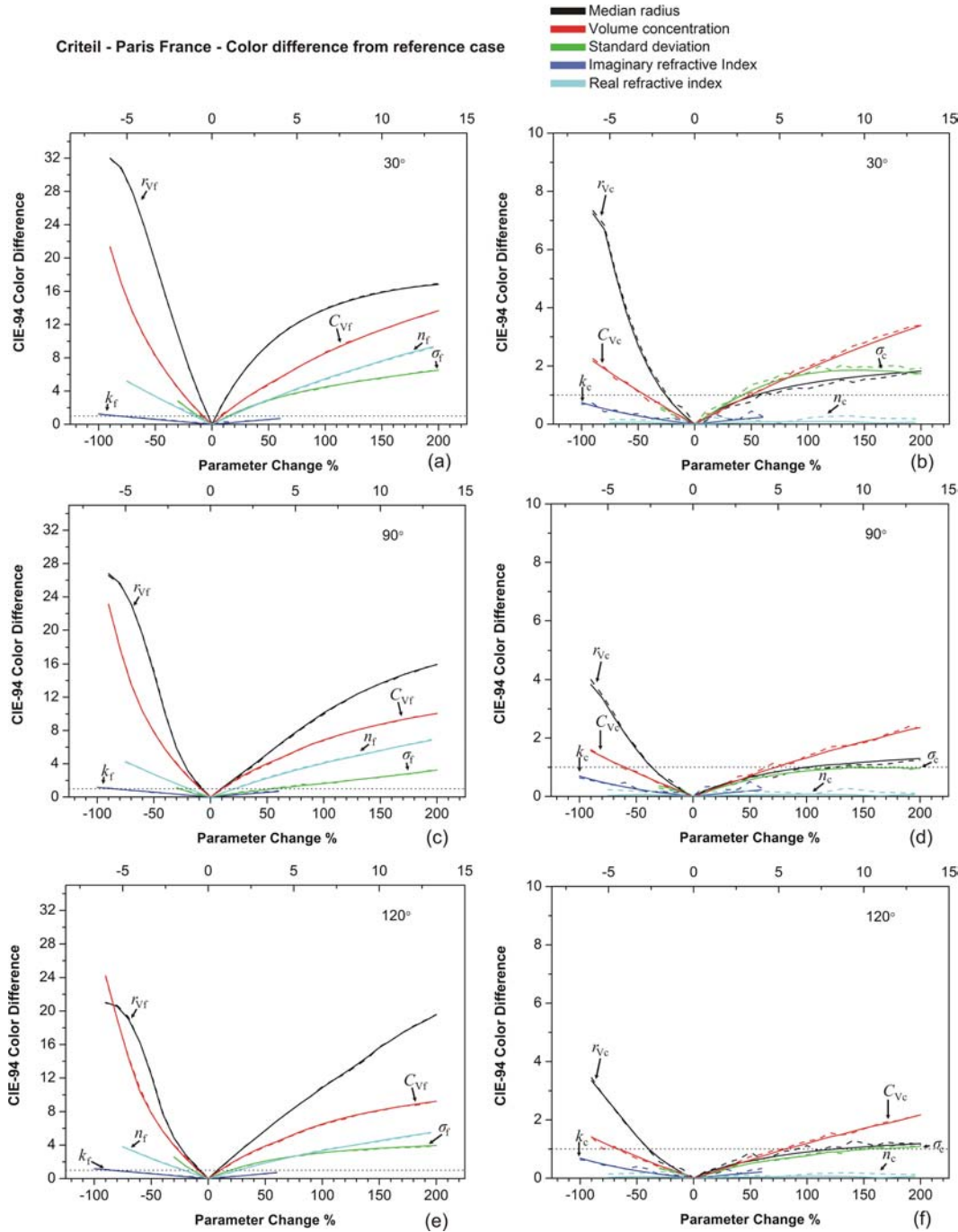


FIG. 5. CIE-94 color difference for the Creteil, Paris aerosol case. Estimated theoretical values (solid lines) and camera measurements (dashed lines). Plates (a), (c), and (e) present the fine mode parameters. Plates (b), (d), and (f) show the coarse mode parameters. The dashed black line intercepts color difference lines at a value of $1 \Delta E_{94}^*$ unit. The n_f curve corresponds to the top x axis and all other curves to the bottom x axis.

and 5 a, c, e). This is the case for all aerosols and all azimuth angles φ . For larger angles, however, this behavior is less noticeable. According to Figure 6 the scattering coefficient varies less when r_{Vf} changes towards larger diameters than when it changes towards the smaller ones. Decreasing r_{Vf} , while keeping C_{Vf} constant, results in an increase of the population of the

particles for that mode. On the other hand, as r_{Vf} decreases, fine mode particles are becoming inefficient scatterers. The combination of the above two competing factors results in an overall decrease of the scattering coefficient of the aerosols (Figure 6, solid black line). Increasing r_{Vf} , initially increases the scattering ability for the majority of the fine mode particles up to a peak

TABLE 2
Summary of the observer sensitivity to the variations of the aerosol parameters

Parameter	Creteil, Paris, France		Mexico City		Maldives (INDOEX)		
	Minimum (%)	Maximum (%)	Minimum (%)	Maximum (%)	Minimum (%)	Maximum (%)	
Azimuth angle $\varphi = 30^\circ$	r_{Vf}	-4.5	5.1	-5.1	5.7	-5.6	6.4
	r_{Vc}	-25.9	54.0	-33.1	118.6	-25.8	55.0
	C_{Vf}	-8.3	8.9	-8.9	9.2	-10.3	12.1
	C_{Vc}	-43.7	49.4	-63.7	76.5	-45.9	55.8
	σ_f	-11.9	14.0	-18.9	24.8	-14.3	15.4
	σ_c	None	41.8	None	54.4	None	37.0
	n_f	-1.0	1.1	-1.1	1.3	-1.7	1.8
	n_c	Not detectable		Not detectable		Not detectable	
	k_f	-81.8	None	-54.5	None	-80.1	84.5
	k_c	Not detectable		-92.7	None	-93.4	None
	Azimuth angle $\varphi = 90^\circ$	r_{Vf}	-8.2	9.5	-8.1	9.0	-9.2
r_{Vc}		-36.5	100.1	-41.9	None	-36.4	102.4
C_{Vf}		-9.0	10.0	-10.4	11.1	-10.6	11.8
C_{Vc}		-59.8	72.9	-82.1	99.4	-62.0	77.3
σ_f		-27.3	55.1	-26.2	38.0	None	42.7
σ_c		Not detectable		None	104.7	None	83.9
n_f		-1.2	1.4	-1.4	1.8	-1.8	1.8
n_c		Not detectable		Not detectable		Not detectable	
k_f		-85.6	None	-54.7	None	-80.1	88.4
k_c		Not detectable		-91.8	None	-93.1	None
Azimuth angle $\varphi = 120^\circ$		r_{Vf}	-8.1	8.5	-6.9	7.6	-7.9
	r_{Vc}	-39.6	125.1	-44.4	None	-39.3	114.5
	C_{Vf}	-9.1	10.2	-10.9	11.9	-10.4	12.1
	C_{Vc}	-66.4	80.6	None	108.6	-64.3	84.0
	σ_f	-13.9	19.2	-14.2	19.9	-12.2	14.1
	σ_c	None	151.8	None	135.7	None	85.2
	n_f	-1.3	1.7	-1.7	2.3	-2.0	2.1
	n_c	Not detectable		Not detectable		Not detectable	
	k_f	-85.1	None	-53.0	None	-77.7	84.3
	k_c	Not detectable		-91.6	None	-94.0	None

^aValues of this table represent minimum to maximum ranges of aerosol parameters variation. Within these ranges the standard human observer is likely not to be able to perceive changes of sky color. "Not detectable" means that for the total range of variation for the particular parameter, color shift remains undetectable by the observer. "None" when present implies that we reached the upper or lower limit of parameter variation and color shift remained unperceived by the observer.

value. A further increase of r_{Vf} results in a decrease of its scattering ability. In addition, increasing r_{Vf} results in a decrease of the aerosol number population. The combination of the above has less abrupt color difference effect than when decreasing r_{Vf} .

At the lower limit of the r_{Vf} variation (-90%) aerosol scattering is small. As a result ΔE_{94}^* is very high (more than 30 units at $\phi = 30^\circ$, Figures 4a, 5a) and the sky colors are closer to those of an optically clearer atmosphere. The stiff slopes of the negative per cent changes of the r_{Vf} curves reveal that the observer of the reference case better comprehends sky color differences be-

tween the aerosol polluted atmospheres relative to an optically clearer than relative to more optically polluted ones.

Table 2 shows that the observer is less sensitive to r_{Vc} . As r_{Vc} decreases from the reference case, more coarse particles enter the fine mode regime and become more efficient scatterers. At the same time the population of the particles increases, further reinforcing coarse mode scattering (Figure 6). The overall result is the rise of the r_{Vc} related ΔE_{94}^* curve of Figures 4, 5 (b, d, f) at the lower parameter limit. Aerosol scattering and correspondingly sky color exhibit slight changes for higher than

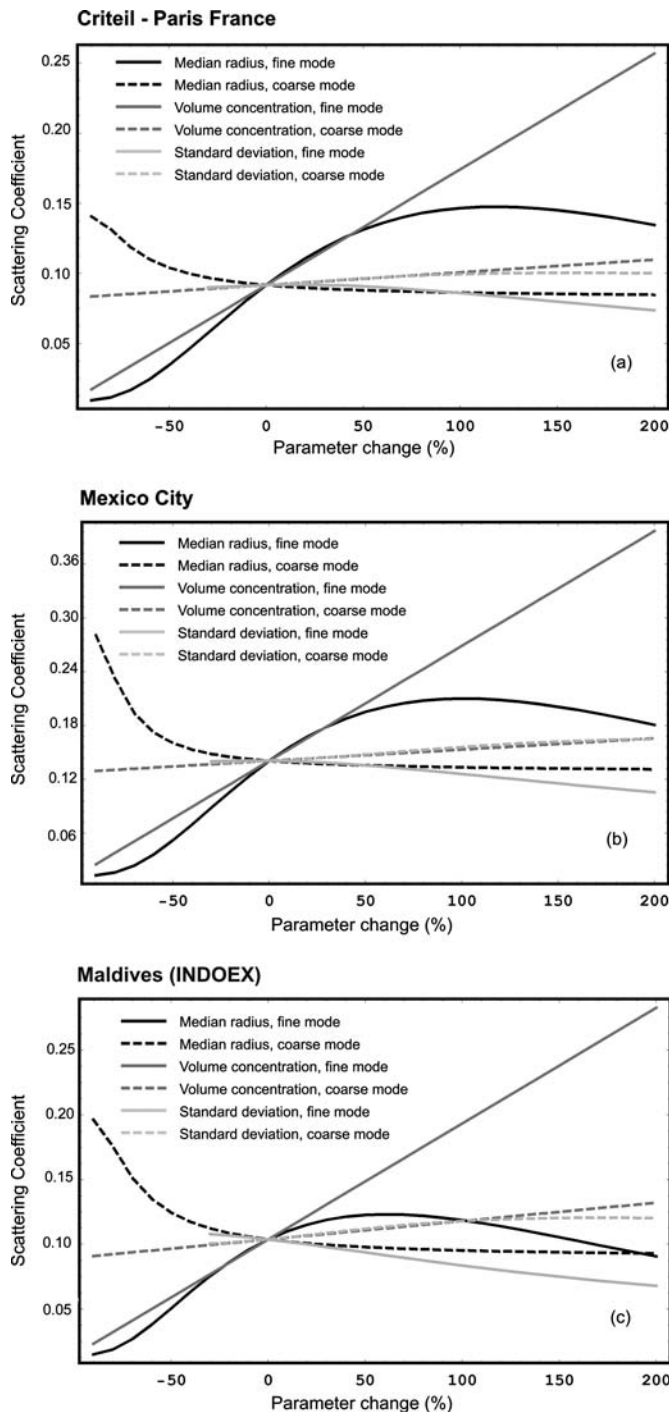


FIG. 6. Scattering coefficients at 550 nm as a function of the variation of the control parameters. The units are in km^{-1} .

the reference case r_{Vc} values. Therefore the sensitivity of the observer is limited (Table 2). According to Table 2 the observer is still capable to detect color changes for large positive percent variations. The slope of r_{Vc} curve of Figures 4 and 5 confirms that if the JND limit is higher than one ΔE_{94}^* unit, then, doubling or tripling this threshold will make color shifts undetectable.

We have also found a strong dependence of both r_{Vf} and r_{Vc} on azimuth angle (Figures 4 and 5). Observer sensitivity decreases from 30° to 90° . Since azimuth angle is directly related to the scattering angle of the single scatter radiation, this dependence can be attributed to the shape of the aerosol phase function.

3.2.2. Variation of the Volume Concentration C_{Vf} and C_{Vc}

We have noted in the previous section that the observer appears to be more sensitive to sky color shifts, when these shifts are driven from diminishing optical pollution, with respect to the reference case. This type of behavior is more evident in the case of C_{Vf} and C_{Vc} variations (Figures 4 and 5). Very low values of volume concentration are related directly to an aerosol free atmosphere. Increasing the volume concentration, while keeping the particles radius fixed, is directly related to increasing the population of the particles and therefore increasing air pollution due to aerosols. As expected from Mie theory, the relation between the aerosol ability to scatter light and the C_{Vf} , C_{Vc} parameters is linear (Figure 6). Although at the upper limit of both C_{Vf} and C_{Vc} variation, the aerosol population is tripled, it is evident from Figures 4 and 5 that the observer is still more sensitive to color variations due to decreasing the aerosol population. Increasing C_{Vc} does not affect the scattering ability of the aerosol substantially, since the latter is dominated by the scattering ability of the fine aerosol. This results in the low magnitude ΔE_{94}^* curves of Figures 4 and 5. Despite this, the observer, as it is shown in Table 2, is capable to detect color changes when the ΔE_{94}^* unit threshold equals one. Once again increasing the ΔE_{94}^* unit threshold makes color shifts undetectable.

According to Table 2, the observer ability to detect color change due to variation of the volume concentration is less affected by the azimuth angle, than in the cases of the r_{Vf} and r_{Vc} variation. This is due to the fact that the variation of the volume concentration does not alter the shape of the aerosol phase function. However, when φ increases, the ΔE_{94}^* curves of Figure 4 tend to rise for very low C_{Vc} values and to decrease for very high C_{Vc} values. This is due to the fact that particles of the fine mode regime and especially those of the coarse regime tend to scatter more radiation in the forward ($\varphi = 30^\circ$) than in the backward ($\varphi = 120^\circ$) directions (Seinfeld and Pandis 1998).

3.2.3. Variation of the Standard Deviation σ_f and σ_c

The ΔE_{94}^* curves of Figures 4 and 5 depict that the observer is not very sensitive to changes of σ_f and especially to those of σ_c . According to Figure 6 the aerosol scattering ability is almost unaffected by changes of σ_f . Table 2 indicates that σ_f variations as small as -1.9% , while $+14\%$ can be detected by the observer. An investigation however of the shape of the curves in both Figures 4 and 5 makes apparent that increasing the ΔE_{94}^* unit threshold will drastically diminish the observer's ability to discriminate color, especially in the case of $\varphi = 90^\circ$ (Figures 4c, 5c). Color variations relevant to changes of σ_c exhibit a dependence on the direction of observation and therefore on the aerosol phase function. A Paris aerosol observer at $\varphi = 30^\circ$ is

more sensitive to σ_f changes than the Maldives and Mexico City observers, while at $\phi = 120^\circ$ the Maldives observer is the most sensitive. Increasing or decreasing σ_f values result in widening or narrowing the particle fine mode band. Increasing σ_f , while keeping C_{Vf} and r_{Vf} fixed, also increases the number of small particles and decreases the number of larger particles of the fine mode. Thus it moves the number distribution of the fine mode towards smaller radiuses that is less efficient in scattering. This results in the limited decrease of the aerosol scattering coefficient (Figure 6). On the other hand, though, the previously described changes of the aerosol distribution have stronger influence on the phase function.

3.2.4. Variation of the Real Part of the Refractive Index n_f and n_c

The lower per cent limit for n_f and n_c variations was set, so that each of the aerosol modes acquires the refractive index of water ($n = 1.33$) (Seinfeld and Pandis 1998). The most sudden color changes are perceived when we perturb the real part of the aerosol fine mode n_f (Figures 4, 5 a, c, e), while the observer is the least sensitive to variations of n_c . For the same changes, aerosols scattering coefficients exhibit large variations for the fine mode and are left invariant for the coarse mode (Figure 7).

Among the three aerosol cases, the Maldives observer is the least sensitive to n_f changes, since, in this case, C_{Vf} has the lowest value (Table 1). The Paris aerosol observer is the most sensitive, while the Mexico City observer is in between (Table 2). These results are in agreement with the scattering coefficients of Figure 7. We can also observe a strong dependence of n_f to changes of the azimuth angle. Observations in the forward direction give better color discrimination than observations in the backward direction. Once more this is attributable to the shape of the aerosol phase function.

3.2.5. Variation of the Imaginary Part of the Refractive Index k_f and k_c

Observers are insensitive to variations of the imaginary part of the refractive index for both aerosol modes, k_f and k_c . These parameters are responsible for the absorption properties of the aerosol (Pilinis and Pandis 1995). Mexico and Maldives aerosols are considered strong absorbing with single scattering albedos $\omega_o(550 \text{ nm})$, of 0.89 and 0.90 and with reference case k_f and k_c at 0.014 and 0.011, respectively. Absorption of Creteil, Paris aerosol is moderate with $\omega_o(550 \text{ nm})$ at 0.94 (Dubovik et al. 2002) and reference case values of k_f, k_c equal to 0.009. For the case of Creteil, Paris aerosol changes remain undetected for the full range of variation of k_c for any angle ϕ , while in all other cases, color differences remain undetected, except when k_c approaches a value of zero (non-absorbing aerosol). The observer of Mexico City aerosol appears to be more sensitive to variations of k_f , but is not accurate. The higher reference case values for both k_f and k_c result in larger deviations from the reference case for the same percent change. For an angle ϕ of 90° we have calculated the magnitude of the k_f decrease needed, in order to reach the $1 \Delta E_{94}^*$ unit threshold. For the Creteil, Paris, Mexico City, and Maldives cases k_f must decrease by 0.0016, 0.0064, and 0.0029, respectively, in order for the observer to detect color shifts. This means that the Paris observer is the most sensitive to changes of k_f .

3.3. Camera Behavior Evaluation

Table 3 presents the statistical evaluation of the agreement between the digital camera and the behavior of the standard observer, with respect to sky color changes. According to the presented results, the camera is in excellent agreement with the behavior of the standard observer, as presented in Section 3.2. The case corresponding to the perturbations of the n_c parameter

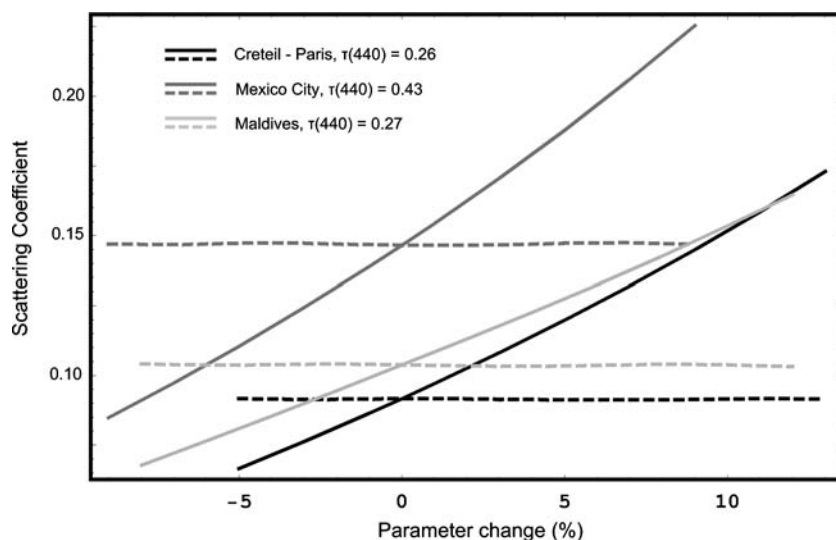


FIG. 7. Scattering coefficients at 550 nm as a function of the variation of the fine mode (solid lines) and coarse mode (dashed lines) refractive indices. The units are in km^{-1} .

TABLE 3
Summary of the camera agreement to the theoretical estimated values of the observer sensitivity

	Parameter	Creteil, Paris, France		Mexico City		Maldives (INDOEX)	
		Slope ^a	Correlation coefficient ^b	Slope ^a	Correlation coefficient ^b	Slope ^a	Correlation coefficient ^b
Azimuth angle $\varphi = 30^\circ$	r_{Vf}	1.00	1.00	1.00	1.00	1.00	1.00
	r_{Vc}	0.97	1.00	1.01	1.00	1.01	1.00
	C_{Vf}	1.00	1.00	1.00	1.00	1.00	1.00
	C_{Vc}	0.96	1.00	1.03	0.99	1.03	0.99
	σ_f	1.00	1.00	1.01	1.00	1.01	1.00
	σ_c	0.92	0.99	1.01	1.00	1.01	1.00
	n_f	1.03	1.00	0.99	1.00	0.99	1.00
	n_c	—	—	—	—	—	—
	k_f	1.05	0.99	0.95	0.99	0.95	0.99
	k_c	1.02	0.91	1.05	0.99	1.05	0.99
Azimuth angle $\varphi = 90^\circ$	r_{Vf}	1.00	1.00	1.00	1.00	1.00	1.00
	r_{Vc}	0.95	1.00	1.01	1.00	0.99	1.00
	C_{Vf}	1.00	1.00	1.00	1.00	1.00	1.00
	C_{Vc}	0.98	1.00	1.01	0.99	1.04	0.99
	σ_f	1.01	1.00	1.02	1.00	1.00	1.00
	σ_c	0.97	0.99	1.07	0.99	1.03	1.00
	n_f	0.99	1.00	1.01	1.00	1.00	1.00
	n_c	—	—	—	—	—	—
	k_f	1.03	0.99	1.00	1.00	0.99	1.00
	k_c	0.93	0.81	1.05	0.99	0.99	0.98
Azimuth angle $\varphi = 120^\circ$	r_{Vf}	1.00	1.00	1.01	1.00	1.01	1.00
	r_{Vc}	1.00	0.99	1.01	1.00	1.01	1.00
	C_{Vf}	1.00	1.00	1.01	1.00	1.01	1.00
	C_{Vc}	0.99	0.99	0.96	0.99	0.96	0.99
	σ_f	1.02	1.00	1.01	1.00	1.01	1.00
	σ_c	0.96	0.99	1.02	1.00	1.02	1.00
	n_f	1.01	1.00	0.99	1.00	0.99	1.00
	n_c	—	—	—	—	—	—
	k_f	1.00	1.00	1.01	0.99	1.01	0.99
	k_c	1.06	0.93	0.94	0.99	0.94	0.99

^aSlope m , is calculated by $m = (\sum_{i=1}^n O_i P_i - \frac{1}{n} \sum_{i=1}^n O_i \sum_{i=1}^n P_i) / (\sum_{i=1}^n O_i^2 - \frac{1}{n} (\sum_{i=1}^n O_i)^2)$, O_i are the estimated CIE-94 color differences based on the camera measurement while P_i are the theoretically predicted color differences. N is the population of O_i or P_i .

^bCorrelation coefficient ρ is calculated by $\rho = m s_o / s_p$, s_o and s_p being the standard deviations of O_i and P_i , respectively.

has not been considered. We have already mentioned that the observer is incapable to discriminate color changes due to variations of n_c . Further analysis of the simulations revealed that n_c changes result in a very limited shift of sky color. In other words, the sky color practically remains constant. Consequently, the statistics in Table 3 for the n_c parameter are meaningless.

3.4. Camera Sensitivity to Variations of the Aerosol Parameters

Camera sensor consists of a two dimensional array of photosites. Each element of the final image (pixel) is estimated by

using information from three photosites (color channels), red, green, and blue. Our model simulates the camera performance. The properties of every image element are the final tristimulus XYZ values calculated from the original sensor color channels recorded values. Since sensors consist of millions of photosites, we can assume that many pixels of the final image practically record the same sky color, especially when using narrow field of view lenses (telephoto lenses). Since our model also incorporates sensor noise sources, each measured X_{rec} , Y_{rec} , Z_{rec} value is paired with the measurement standard deviations σ_X , σ_Y , and σ_Z . Let $X_{rec,bc}$, $Y_{rec,bc}$, and $Z_{rec,bc}$ be the sky color reference case tristimulus values measured by the camera and $\sigma_{X,bc}$, $\sigma_{Y,bc}$,

TABLE 4
Summary of the camera sensitivity to the variations of the aerosol parameters

Parameter	Creteil, Paris, France		Mexico City		Maldives (INDOEX)		
	Minimum (%)	Maximum (%)	Minimum (%)	Maximum (%)	Minimum (%)	Maximum (%)	
Azimuth angle $\phi = 30^\circ$	r_{Vf}	-0.19	0.30	-0.29	0.36	-0.27	0.39
	r_{Vc}	-1.68	2.56	-6.70	2.54	-2.13	2.49
	C_{Vf}	-0.55	0.96	-0.91	0.96	-0.54	1.19
	C_{Vc}	-3.46	2.72	-6.56	4.18	-3.34	4.67
	σ_f	-1.91	1.70	-1.74	2.84	-0.82	0.59
	σ_c	-2.50	3.20	-5.80	4.36	-3.71	2.36
	n_f	-0.09	0.15	-0.14	0.22	-0.12	0.29
	n_c	Not detectable		Not detectable		Not detectable	
	k_f	-2.93	1.67	-2.52	1.26	-1.88	3.07
	k_c	-4.22	10.64	-2.48	5.71	-8.45	1.93
Azimuth angle $\phi = 90^\circ$	r_{Vf}	-1.54	0.67	-0.62	0.60	-0.43	0.44
	r_{Vc}	-3.07	4.63	-4.59	3.36	-2.64	6.80
	C_{Vf}	-0.65	0.90	-0.93	0.97	-0.85	0.83
	C_{Vc}	-2.80	6.28	-4.83	4.58	-4.04	4.27
	σ_f	-1.86	7.66	-1.86	3.80	-1.27	2.10
	σ_c	-2.47	3.80	-2.31	6.09	-3.60	3.56
	n_f	-0.10	0.10	-0.14	0.15	-0.14	0.08
	n_c	Not detectable		Not detectable		Not detectable	
	k_f	-3.32	3.47	-2.26	1.79	-2.45	3.35
	k_c	-6.26	3.38	-4.70	4.40	-2.89	3.65
Azimuth angle $\phi = 120^\circ$	r_{Vf}	-0.42	0.32	-0.30	0.34	-0.33	0.43
	r_{Vc}	-2.68	2.89	-2.13	5.90	-3.59	5.74
	C_{Vf}	-1.00	0.79	-0.92	1.20	-0.94	1.09
	C_{Vc}	-4.96	3.78	-5.05	2.99	-5.73	3.83
	σ_f	-0.73	0.70	-0.68	0.95	-0.42	0.75
	σ_c	-3.35	3.84	-5.81	7.06	-3.93	2.76
	n_f	-0.11	0.17	-0.17	0.27	-0.15	0.15
	n_c	Not detectable		Not detectable		Not detectable	
	k_f	-1.78	3.91	-1.89	2.08	-1.97	2.59
	k_c	-9.38	4.21	-7.35	4.45	-2.60	4.88

^aValues of this table represent minimum to maximum ranges of aerosol parameters variation. Camera sensitivity estimations are based on 500 sensor photosites. Within these ranges the camera will not be able to perceive changes of sky color. "Not detectable" means that for the total range of variation for the particular parameter, color shift remains undetectable by the camera.

and $\sigma_{Z,bc}$ their uncertainties. For a single pixel we define the Signal-to-Noise Ratio (SNR) relative to the reference case for the X color coordinate:

$$SNR_X = \frac{|X_{rec} - X_{rec,bc}|}{\sqrt{\sigma_X^2 + \sigma_{X,bc}^2}} \quad [5]$$

$\sqrt{\sigma_X^2 + \sigma_{X,bc}^2}$ being the standard deviation of $|X_{rec} - X_{rec,bc}|$ difference, by application of the law of error propagation (Mandel 1984). The above equation can be changed in order to include information from a total number of m_p pixels with similar

$$SNR_X = \frac{|\langle X_{rec} \rangle - \langle X_{rec,bc} \rangle|}{\sqrt{\left(\frac{\sigma_X}{\sqrt{m_p}}\right)^2 + \left(\frac{\sigma_{X,bc}}{\sqrt{m_p}}\right)^2}} \quad [6]$$

$\langle X_{rec} \rangle$ and $\langle X_{rec,bc} \rangle$ being the average values of m_p pixels. SNR_Y and SNR_Z are defined accordingly. There are various ways to choose the SNR that one can use in order to examine whether the camera can detect sky color shifts. For reasons of simplicity we have defined the camera SNR as the average of

the XYZ SNRs:

$$SNR = (SNR_X + SNR_Y + SNR_Z)/3 \quad [7]$$

Camera can positively detect a color change if the above SNR has a value above one unit. This practically means that the recorded data participating in the estimation of $|\langle X_{rec} \rangle - \langle X_{rec,bc} \rangle|$ are stronger than the inherent noise of these data. The results presented below are similar regardless of the choice of the SNR.

Table 4 presents the results of the camera sensitivity relative to the variations of the ten aerosol control parameters. Table 4 was constructed in a similar way to Table 2, e.g., by assuming a threshold of 1 SNR unit. We used 500 image elements to estimate camera SNRs ($m_p = 500$). The camera is far more sensitive than the human observer. Once more, color shifts caused by changing the parameters of the fine mode are more easily detected than changes of the coarse mode. The camera, however, is also very sensitive to changes of the coarse mode. It is interesting to note that the camera appears more sensitive to r_{vf} than the n_f parameter. This contradicts the results of Table 2. It appears that the actual color is more sensitive to changes of r_{vf} but, due to the properties of the human vision, the observer mostly understands changes of n_f . According to Table 4 the camera sensitivity is dependent on the type of urban-industrial aerosol and on the azimuth angle ϕ . In many cases the values in Table 4 are highly correlated to those of Table 2. Since almost no color shifts occur when changes of n_c take place, SNR values were very low and no color difference could be identified by the camera measurements.

4. SUMMARY AND CONCLUSIONS

The sensitivity of the human observer to shifts of the sky color relative to changes of various urban-industrial aerosol parameters has been studied. Detail knowledge of the human observer reactions is useful in understanding the importance of the various aerosol properties, when related to visibility and visual air quality. Results from the three urban-industrial aerosols used, reveal that the observer is more sensitive to changes of the fine than the aerosol coarse mode. The observer is most sensitive to changes of the fine mode real part of the refractive index, n_f , and of the median radius, r_{vf} following by changes of the volume concentration C_{vf} , and of the mode standard deviation, σ_f . On the contrary, changes of coarse mode real part of the refractive index, n_c are not detectable, while changes of that modes k_c , and σ_c are hard to detect. The results of this analysis can be used to explain how the observer will respond, when physico-chemical changes of the atmospheric aerosols occur over a city. Consider, for example the scenario of an aerosol population undergoing growth, due to an increase of the ambient relative humidity. Hygroscopic growth is always associated with shifting the aerosol fine mode distribution towards the coarse mode (Pilinias and Pandis 1995) and increasing the volume concentration (Dubovik et al. 2002).

This also results in lower values of n_f due to water uptake of the aerosol particles. According to Table 2, in this scenario, the observer is capable of detecting changes of n_f as low as of $\pm 1\%$, in the case of r_{vf} as low as $\pm 4.5\%$ and in the case of C_{vf} as low as $\pm 8.5\%$ in magnitude. Obviously all changes contribute to the perception of color shifts, but the reference case observer mostly understands changes due to n_f perturbation and secondly to r_{vf} and C_{vf} .

A specialized camera system equipped with the appropriate software that converts tristimulus XYZ values to CIE-94 color difference estimations can closely replicate the behavior of the standard observer. We have proven that the camera, can replicate the behavior of the observer to sky color changes. This study shows that such a camera system could be used to investigate further the sensitivity of humans to sky color shifts, when these shifts are related to the aerosol characteristics. The same system is also useful for predicting the observer reaction to these color changes.

We have also shown that the camera is more sensitive to color shifts than the human observer. This implies that the camera could be used as a monitoring system. Since camera is more sensitive than the observer in detecting color differences such a device can be used to study and to monitor sky color changes that result from pollution episodes.

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